ΗΙΟΚΙ

POWER ANALYZER PW3390



High Accuracy Power Analysis. Anywhere, Anytime.

High Accuracy and Mobility. A New Value for Power Analysis.

The original HIOKI POWER ANALYZER 3390, released 8 years ago, featured the latest measurement technology built into a compact casing.

Pair with Hioki current sensors and take them anywhere to immediately make highly accurate measurements.

This was the unique value of the 3390.

Now, Hioki has enhanced this value while refining the measurement technology even further.

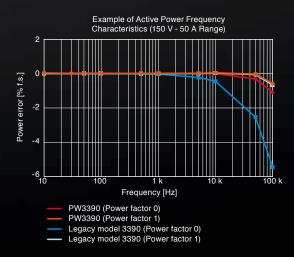
Proper accuracy and bandwidth to precisely measure inverter output. Phase shift function for the exact measurement of high frequency, low power factor power. A broad current sensor lineup that expands the range of measurement possibilities.

Refinements that empower you to conduct precise power analysis in any situation.



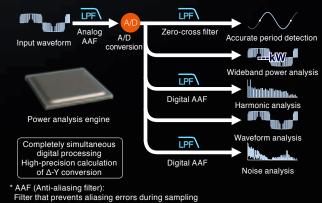
Complete Pursuit of Measurement Accuracy and High Frequency **Characteristics**

The PW3390 delivers 4 input channels and ±0.04% basic accuracy for power - the top instrument in its class. Achieve more precise measurements of the power and efficiency of high efficiency equipment used in power electronics. Further, a 200 kHz measurement band and flat amplitude and phase characteristics up to high frequencies enable the precise measurement of power at top frequency levels and low power factor.



Power Analysis Engine That Achieves High-Speed Simultaneous Calculation on **5** Systems

Precisely capture input waveforms with 500 kS/s high-speed sampling and a high resolution 16-bit A/D converter. The power analysis engine performs independent digital processing for 5 systems: period detection, wideband power analysis, harmonic analysis, waveform analysis, and noise analysis. High-speed simultaneous calculation processing enables both precise measurements and a 50 ms data refresh rate.



Current Sensors for the Thorough Pursuit of High Accuracy. Achieve Superior Accuracy for High-Frequency, Low Power Factor Power.

High Accuracy Sensor Pass-Through Type

Pass-through type with high accuracy and a wide measurement range. Conduct extremely accurate measurements of large currents to a maximum of 1000 A over a wide operating temperature range.

High Accuracy Sensor Clamp Type

Clamp for quick and easy connections. Conduct extremely accurate measurements of large currents to a maximum of 1000 A over a wide operating temperature range.

High Accuracy Sensor Direct Wire Type

Newly developed DCCT method delivers expansive measurement range and superior measurement accuracy at a rating of 50 A.

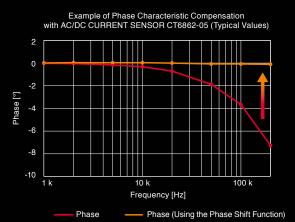






Built-in Current Sensor Phase Shift Function

Equipped with new virtual oversampling technology. Achieve phase shift equivalent to 200 MS/s while maintaining a high speed of 500 kS/s, as well as a high resolution of 16 bits. Set and correct the phase error of the current sensor at a resolution of 0.01°. Use of the phase shift function results in a dramatic reduction of measurement error. This allows the measurement of high-frequency, low-power factor power included in the switching frequency of inverter output, which is difficult to measure with conventional equipment.



Virtual oversampling: Technology that uses a sampling frequency several hundred times higher than the actual sampling frequency to perform virtual deskewing

In the Laboratory or in the Field

Take Highly Accurate Measurements Even in Tough Temperature Conditions

Severe temperature environments, such as engine rooms with intense temperature changes and constant temperature rooms, can hinder high accuracy measurements. The extremely accurate pass-through and clamp type sensors both feature excellent temperature characteristics and a wide operation temperature range to help address these challenges.



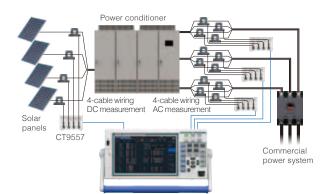
Max. 6000 A Measurement on 50 Hz/60 Hz Lines

The CT7040 AC FLEXIBLE CURRENT SENSOR series can measure commercial power lines up to 6000 A, including solar power conditioner output. Even thick cables can be wired easily among crowded wiring or in narrow locations.



New Method for Measuring Large Current over Multi-Cable Wiring

Highly accurate measurement of current in multi-cable wiring with large currents has been difficult-until now. The CT9557 adds the output waveforms from the high accuracy sensors connected to each branch line of the multi-cable wiring, for the highly accurate measurement of large currents.



Achieve High Accuracy Measurement Even in the Field

Dramatically compact and light-weight form factor achieved by concentrating the calculation functions in the power analysis engine. Highly accurate measurements normally achieved in the laboratory are now also possible in the field.



External Power Supply Not Needed for Sensor Connections

Power can be supplied to the current sensor from the main unit, so there is no need to provide a separate external power supply for the current sensor. Connected sensors are recognized automatically, for reliable and quick measurements.



Wiring Displays and Quick Setup Lets You Begin Measuring Immediately

Perform wiring while checking wiring diagrams and vectors on the screen. Optimum settings are performed automatically simply by selecting a connection and using the quick setup function.

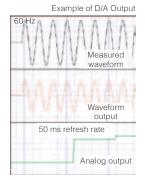


Extensive Interface for Linking with External Devices

Wide variety of built-in interfaces, including LAN, USB (communication, memory), CF cards, RS-232C, synchronization control, and external control.

D/A output* delivers analog output at 50 ms for up to 16 parameters. The voltage and current waveform** for each channel can also be output.





* Built-in for PW3390-02 and PW3390-03

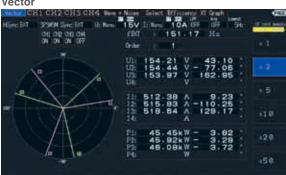
** During waveform output, accurate reproduction is possible at an output of 500 kS/s and with a sine wave up to 20 kHz.

Switch Screens with a Single Touch, Accessing a Variety of Power Analysis Methods

The power analysis engine allows the simultaneous, parallel calculation of all parameters. Access a variety of analysis methods simply by pressing the page keys to switch screens.

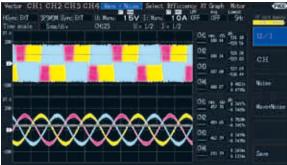


Vector



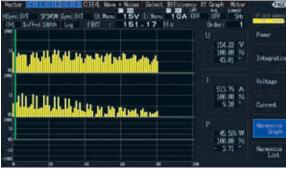
Confirm the voltage/current/power/phase angle for each harmonic order on a vector graph and as numerical values.

Waveform



Display voltage/current waveforms for 4 channels at a high speed of 500 kS/s or a maximum length of 5 seconds. Waveform data can be saved.

Harmonics Graph



Display harmonics up to the 100th order for voltage/current/power in bar graphs. Confirm the numerical data for the selected order at the same time.

Efficiency and Loss

| Vector CH1 CH2 C | налан | 4 Wave + Noise Select Effects | Ki Graph Rotor G23- |
|------------------|-------|---------------------------------|---------------------|
| 71 | 4 | 85.75 | % |
| 72 | | 78.88 | % |
| 73 | | 67.64 | % |
| Lossi | 3 | 0.0236k | w |
| Loss2 | 3 | 0.0300k | w |
| Loss3 | - | 0.0535k | w |

Using active power values and motor power values, confirm efficiency η [%] and loss [W] and total efficiency for each inverter/motor on a single unit at the same time.

Selection Display

| Unel | 85.01 | V. | Unt | 85.01 | V. | Old Rangel | 4 time |
|-----------|--------|-------|---------|--------|---------|----------------|----------|
| Ume2 | 85.22 | v | Us:2 | 85.22 | V. | Ultrane UN | |
| Une3 | 84.63 | ¥ ¥ ¥ | Und | 84.63 | **** | I Minis 105 | |
| Unet | 480.84 | v | Unot | 0.38 | v | | I itimi |
| Inel | 455-18 | A. | I and | 455.18 | A. | CH2 Range | |
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| Ired. | 459.94 | A. | Ind: | 459.94 | A | I Kini UM | 16 item |
| Inef | 193.27 | A | I Inot. | 25.98 | Α | | |
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| P3 | 22.50k | w | 53 | 22.56k | VA. | Littlevic 1988 | |
| P4 | 92.09k | W | 54 | 92.93k | VA. | Oit kings | |
| #1 | 74.285 | H= | AL. | 0.9958 | | UKana Silv | |
| 42. | 74.280 | HE | A2 | 0.9990 | | 1 Martin 1985 | |
| 13 | 74.283 | He | 1.1 | 0.9971 | | • MALINE MADE | |
| 00001001 | 0.0000 | He | M | 0.9909 | | | Select |

Select 4/8/16/32 display parameters individually for each screen, and summarize them on a single screen.





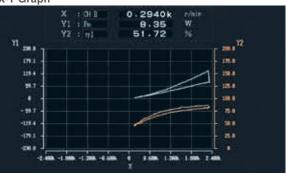
Display FFT results for voltage and current as graphs and numerical values, up to a maximum of 100 kHz. This is perfect for the frequency analysis of inverter noise.

Power

| Vector CH | | H2ICH5 CH | 14 line | | | Efficiency XI (| | 1 | (B) |
|------------------------|-----|--------------------------------------|----------|----------------|--------|----------------------------|----------------|----|--------------------|
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| 0m(23 | | 160.51 | A. | 8123 | | 163.06k | A.V | | Integration |
| 1 read 1 read | | 513.64 | \$ | - 11 - 12 | | 27.58k | | | |
| I read I read | 4 | 519.58 | 2 | 03 01 21 | | 27.29k 02.41k | | | Valtage |
| 1222 | | 46.47k 46.97k 47.25k | ar ar | 41 42 43 | | 30.69 30.38 30.01 | | | Cerest. |
| P123 | | 140.69k | | #123 | | 30.36 | | | Herenica Gright |
| A1 A2 A5 A123 | | 0.8599 0.8627 0.8659 0.8659 | | 11 12 13 | | 151.27 151.11 151.26 | Ha Ha Ha | | Heronica List |

On the basic measurement screen, display voltage/current/power/power factor/frequency and other parameters in a list for each connection.

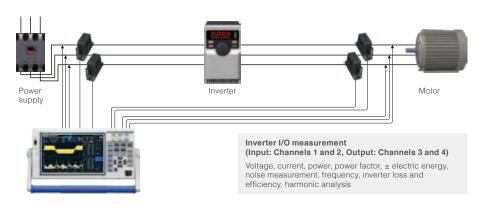
X-Y Graph



Create inverter characteristic evaluations and motor torque maps. Select the desired parameter to display an X-Y plot graph.

Applications

Measure the Power Conversion Efficiency of Inverters

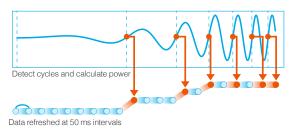


Key features

- Isolated input of voltage and current on each of 4 channels for simultaneous measurement of the primary and secondary power of inverters
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental components
- Easy wiring with current sensors. Reliable confirmation of wiring with vector diagrams
- Current sensors reduce effects of common mode noise from inverters during power measurement
- Simultaneous measurement of noise components, in addition to the harmonic analysis required for the measurement of inverter control

Highly Accurate and Fast 50 ms Calculation of Power in Transient State

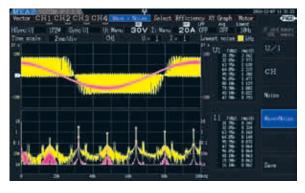
Measure power transient states, including motor operations such as starting and accelerating, at 50 ms refresh rates. Automatically measure and keep up with power with fluctuating frequencies, from a minimum of 0.5 Hz.



Automatic detection of fundamental wave even if the frequency fluctuates, from low to high frequencies

Measure High-Frequency Noise in Inverters

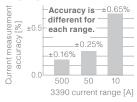
Power supply problems caused by high switching inverter frequencies are unrelated to the fundamental frequency, making it difficult to conduct proper harmonic analysis. The noise analysis function performs a frequency analysis of noise components up to 100 kHz, and displays the frequency, and voltage and current levels for the top 10 points. This is effective for measuring high-frequency noise in inverters.



Combined Accuracy of Current Sensors Applicable throughout Entire Range

Combined accuracy throughout the entire range is provided through the use of a built-to-order high accuracy pass-through type current sensor. Obtain highly accurate measurements regardless of range, from large to minute currents, even for loads that fluctuate greatly.

Legacy Model 3390



Combination of 3390 and 9709 (500 A rating) Total Accuracy when measuring currency of 45 to 66 Hz and f.s. for each range



Combination of PW3390 and the high accuracy 9709-05* (500 A rating, built-to-order) Total accuracy when measuring currency of 45 to 66 Hz and f.s. for each range

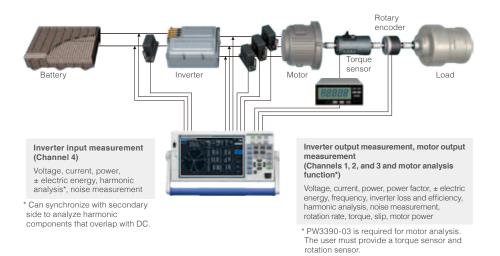
* High-accuracy specifications are not defined for the built-to-order high accuracy current sensor when used alone.

Acquire Data from up to 8 Synchronized Units (32 Channels)

When you connect CONNECTION CABLE 9683 to multiple PW3390 units, the control signals and internal clocks synchronize. From the master unit, you can control the measurement timing on the PW3390 units that are set as slaves. With interval measurement, you can save synchronized measurement data to a CF card or a PC to achieve simultaneous measurements across a larger number of systems.



Analyze and Measure EV/HEV Inverter Motors



Key features

- Easy wiring and highly accurate measurements with the use of a pass-through type current sensor
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental components
- 3. 0.5 Hz to 5 kHz harmonic analysis without external clock
- Total measurement of inverter motors with built-in motor analysis function
- Measurement of the voltage, torque, rotation rate, frequency, slip, and motor power required for motor analysis with a single unit
- More precise measurements of electrical angle with incremental type encoders

Electric Angle Measurement of Motors (PW3390-03 only)

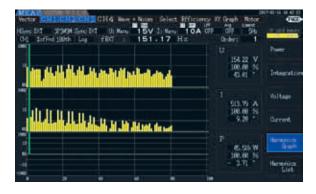
The PW3390-03 features a built-in electric angle measurement function required for vector control via dq coordinate systems in high-efficiency synchronized motors. Make real-time measurements of phase angles for voltage and current fundamental wave components based on encoder pulses. Further, zero-adjustment of the phase angle when induced voltage occurs allows electric angle measurement based on the inductive voltage phase. Electric angle can also be used as an Ld and Lq calculation parameter for synchronized motors.



Display motor electric angles on the vector screen

Measure Harmonics with Consideration for PWM Waveform Characteristics

The zero-crossing filter automatically matches the input frequency in the range of 0.5 Hz to 5 kHz to reliably detect the fundamental frequency. Further, harmonic analysis that is based on the fundamental frequency automatically prevents aliasing error using a digital AAF, which allows both precision and measurement reproducibility at a high level.

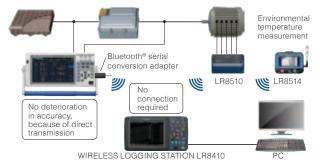




Motor analysis screen (Torque, rotation rate, motor power, slip) For CH B, enter the Z-phase pulse of the encoder to measure electric angle, and enter the B-phase pulse to measure rotation direction.

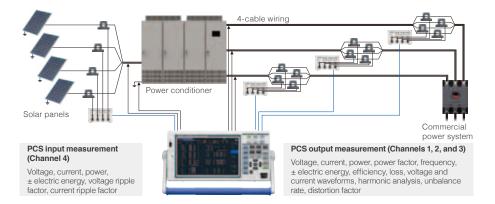
Transfer to Data Logger via Bluetooth[®] wireless technology

Connect the PW3390 and a data logger (with support of LR8410 Link) via Bluetooth[®] wireless technology to wirelessly transmit 8 parameters of measurement values from the PW3390 to the data logger. In addition to the voltage, temperature, humidity, and other parameters measured by the multichannel data logger, you can also integrate the measurement values of the PW3390 and observe and record them in real time.



* Connection requires the serial - (Bluetooth[®] wireless technology) conversion adapter and power supply adapter recommended by Hioki. Please inquire with your Hioki distributor.

Measure the Efficiency of PV Power Conditioners (PCS)



Key features

- 4 built-in channels, standard. Simultaneously measure the I/O characteristics of power conditioners.
- Current sensors can measure even large currents with high accuracy. Reliable confirmation of wiring with vector diagrams.
- Measure the amount of power sold/ purchased from power conditioner output on interconnected systems with a single unit.
- DC mode integration function, which responds quickly to input fluctuations such as with solar power, built in.
- Measure ripple factor, efficiency, loss, and all other parameters that are required for the measurement of power conditioners for solar power with a single unit.

HIOKI's Current Measurement Solutions for Large Currents of 1000 A or More

Introducing a lineup of sensors taking measurements up to 6000 A for 50 Hz/60 Hz, and up to 2000 A for direct current. The CT9557 SENSOR UNIT lets you add the output waveforms from multiple high accuracy sensors. Use multi-cable wiring lines to take highly accurate measurements of up to 4000 A.

| | | | Blue: High accuracy sensor | Black: Normal sensors | | |
|----------------|------------------------------------|----------|-------------------------------|--------------------------|---------|---|
| curren | mended t sensor ement target | DC power | System power 50 Hz/60 Hz | Inverter secondary power | | CT6865-05 (AC/DC 1000 A) Pass-through type; Wideband, high accuracy |
| 1000 A or less | | | CT6865-05 or CT6846-05 | 1 | - | CT6846-05 (AC/DC 1000 A) Easy-connect clamp type CT9557 |
| | 1-cable wiring | CT7742 | CT7642 | - | 1111 | Add waveforms from multiple current sensors |
| 2000 A or less | 2-cable wiring | CT9557 + | CT6865-05 x 2 or CT9557 + CT6 | 846-05 x 2 | <u></u> | CT7742 (AC/DC 2000 A) Stable measurement of DC without zero |
| 4000 A or loop | Less than 4-cable wiring | - | CT7044/CT7045/CT7046 | - | ~ | offset CT7642 (AC/DC 2000 A) |
| 4000 A of less | 4-cable wiring | | CT6865-05 x 4 or CT9557 + CT6 | 846-05 × 4 | × 4 | Wider frequency characteristics than the CT7742 |
| 6000 A or less | | - | CT7044/CT7045/CT7046 | - | | CT7044/ CT7045/ CT7046 (AC 6000 A) Flexible, for easy connections even in narrow gaps |

Support for PCS Parameters

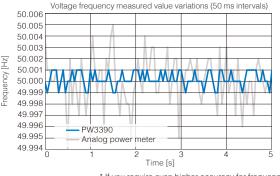
Simultaneously display the parameters required for PCS, such as efficiency, loss, DC ripple factor, and 3-phase unbalance rate. Easily check the required measured items for improved test efficiency. By matching the measurement synchronization source for both input and output, you can perform DC power measurements that are synchronized with the output AC as well as stable efficiency measurements.

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|-----------------------|---|--------|---|---|
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| $U_{\rm thdl}$ | | 2.390 | X | ١ |
| U _{wb} | | 0.306 | X | ι |
| Loui | | 0.546k | W | L |
| | | | | |

DC power (panel output)
 3-phase power (PCS output)
 Conversion efficiency
 Ripple factor
 Frequency
 Voltage total harmonic distortion
 Unbalance rate
 Loss

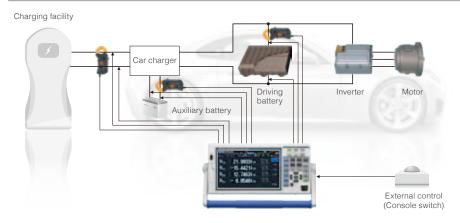
±0.01 Hz^{*} Basic Accuracy for Voltage Frequency Measurements

Perform the frequency measurements that are required for various PCS tests with industry-leading accuracy and stability. Take highly accurate frequency measurements on up to 4 channels simultaneously, while also measuring other parameters at the same time.



^{*} If you require even higher accuracy for frequency, please inquire with your local Hioki distributor.

Test Automobile Fuel Economy

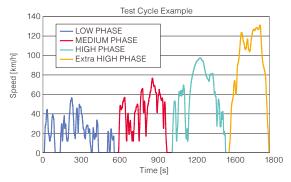


Key features

- 1. Accurately measure recharge and discharge power with excellent basic accuracy and DC accuracy.
- 4 built-in channels, standard. Support for multiple recharge and discharge measurements, including auxiliary batteries.
- Easily achieve highly accurate measurements with clamp sensors, which can be used in a wide range of operating temperatures.
- Easily link with other measuring instruments through integration control with an external control interface.

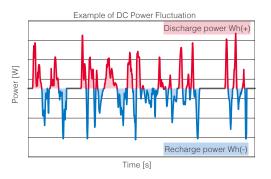
Evaluate WLTC Mode Performance - A New Fuel Economy Standard

Taking fuel economy measurements that comply with WLTP international standards requires the precise measurement of current integration and power integration for the recharging/ discharging of each battery in the system. High accuracy clamp current sensors, the excellent DC accuracy of the PW3390, and the ability to integrate current and power at 50 ms intervals are extremely effective in meeting this application.



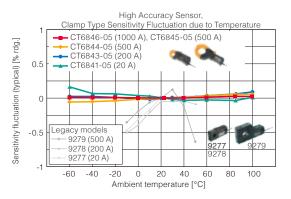
Current and Power Integration Function by Polarity

DC integration measurement integrates the recharging power and discharging power by polarity for every sample at 500 kS/s, and measures positive-direction power magnitude, negative-direction power magnitude, and the sum of positive- and negative-direction power magnitude during the integration period. Accurate measurement of recharging power and discharging power is possible even if there is rapid repetition of battery recharging/discharging.



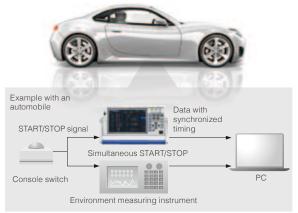
Optimal Current Sensors for Automotive Testing

Easily connect high accuracy clamp-type sensors without cutting the cables. Sensors operate over a temperature range of -40°C to 85°C (-40°F to 185°F), characteristics that enable highly accurate measurements even inside the engine room of a car.

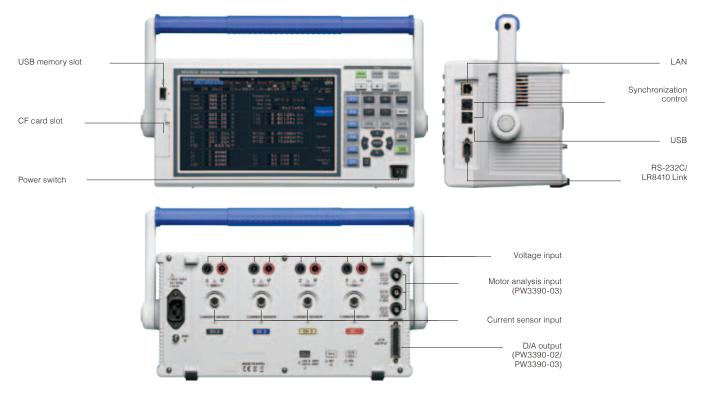


Link to Peripheral Devices via External Control

Use external control terminals to START/STOP integration and capture screen shots. This makes it easy to control operations from console switches and link to the timing of other instruments when measuring the performance of an actual automobile.



External Appearance



Software

Download software, drivers, and the Communications Command Instruction Manual from the Hioki website. https://www.hioki.com

"PW Communicator" PC Communication Software

PW Communicator is an application program for communicating between a PW3390 series power analyzer and a PC. It includes many useful functions, such as configuring PW3390 settings, monitoring measurement values, saving CSV data, and calculating efficiency.

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| ave onit eter | erical value oring form oring r setting ure with ole units rd in CSV | Display the PW3390's m to 32 values, such as vol Monitor the measured vo Change the settings of th In addition to the PW339 from the HIOKI PW600 Power Meter series. You | tage, current, p iltage, current, ne connected F 0, it is also poor 1 Power Anal can also simu ations for mea | ower, and harmo and waveforms o PW3390 from the I ssible to perform I yzer and the PW litaneously record suring instruments | nics. n the PC scre PC screen. Datch control 3335, PW33 measured da S. | en. of up to 8 devic 36, and PW33 ata to the PC, ar | ees 37 nd | | envi | rating | | F F C C V V V V V V C (C C C C C C C C C C | PC/AT- compu- Vindor Vindor 32bit/ Windor 32bit/ Windor 32bit/ Windor 32bit/ Windor 32bit/ Windor 32bit/ Windor 2000 States countr | -compat iter ws 10 ws 8 ws 7 64bit) ows is a hark of M ration in and/or of | ible registere licrosoft the Unite ther |

LabVIEW Driver

Obtain data and configure measurement systems with the LabVIEW driver.

* LabVIEW is a registered trademark of NATIONAL INSTRUMENTS.

Specifications

Basic Specifications

Accuracy guaranteed for 6 months (and 1.25 times speci-fied accuracy for one year) Post-adjustment accuracy guaranteed for: 6 months ations

| Measurement line type | Single-phase 2- | wire (1P2W), Sir | ngle-phase 3-wir | e (1P3W), 3-pha | se 3-wire |
|---|--|---|--|---|---|
| | (3P3W2M, 3P3V | | | СНЗ | CH4 |
| | Pattern 1 | 1P2W | 1P2W | 1P2W | 1P2W |
| | Pattern 2 | | 3W | 1P2W | 1P2W |
| | Pattern 3 | | W2M | 1P2W | 1P2W |
| | Pattern 4 Pattern 5 | | 3W W2M | 1P: 1P: | |
| | Pattern 6 | | W2M | 3P3\ | |
| | Pattern 7 | | 3P3W3M | | 1P2W |
| Number of input | Pattern 8 Voltage: 4 chanr | | 3P4W | | 1P2W |
| channels Measurement input | Current: 4 chanr Voltage: Plug-in | jacks (safety jac | cks) nectors (ME15W) | | |
| terminal type Input methods | Voltage: Isolated | d inputs, resistiv | . , | it) | |
| Voltage range | 15 V/30 V/60 V/1 | 50 V/300 V/600 | | | able.) |
| Current range | 2 A/4 A/8 A/20 A | | ining oyotom. A | - | 9272-05, 20 A) |
| (): Sensor used | 0.4 A/0.8 A/2 A/4 4 A/8 A/20 A/40 4 A/80 A/200 A | A/80 A/200 A (/400 A/800 A/2 A/1 A/2 A/5 A (/20 A/50 A 100 A/200 A/50 /200 A/400 A/1 A A/4 kA/8 kA A/4 kA/8 kA/20 A/80 A/200 A A/80 A/200 A | 0 A kA kA | (200 A set (2000 A set (5 A sens) (50 A set (500 A set) (500 | sensor) sor) isor) ensor) ensor) and CT7742) , CT7045, 246) A sensor) sensor) sensor) A sensor) |
| Power range | | omatically by the nt line. | combination of | | , |
| Crest factor | 300 (relative to r 3 (relative to vol | ninimum effectiv tage/current ran | ve voltage/curren ge rating) (for 15 | t input) (for 1500 00 V range: 1.33 |) V range: 133)) |
| Input resistance (50 Hz/60 Hz) | Voltage input sec Current sensor in | | : 2 MΩ ±40 kΩ (dif : 1 MΩ ±50 kΩ | ferential input and | d insulated input |
| Maximum input voltage | Voltage input se Current sensor i | | 1500 V, ±2000 \ 5 V, ±10 Vpeak | /peak | |
| Maximum rated voltage to earth | | ategories III 600 | 0 Hz/60 Hz) V (anticipated tra V (anticipated tr | | |
| Measurement method | zero-crossing ca | | f voltage and cur d | rent, simultaneo | us |
| Sampling | 500 kHz/16 bit | | | | |
| Measurement frequency range | DC, 0.5 Hz to 20 | 10 kHz | | | |
| Synchronization frequency range | 0.5 Hz to 5 kHz Selectable lower | limit measureme | ent frequency (0.5 | Hz/1 Hz/2 Hz/5 | Hz/10 Hz/20 Hz |
| Synchronization source | pulse input), DC (50 ms or 10 Selectable for ea the same synchr The zero-crossin Two filter levels (Operation and ac | 0 ms fixed) ach measuremen onization source g filter automatic strong or mild) curacy are undete ccuracy are dete | notor evaluation ir nt channel (U/I for e) ally matches the d ermined when the c ermined when U c | each channel m igital LPF when L zero-crossing filte | easured using I or I is selected. r is disabled (off) |
| Data update interval | 50 ms | | | | |
| LPF | 500 Hz: Accurac 5 kHz: Accuracy | y defined at 60 defined at 500 | ectable for each Hz or below (Ado Hz or below) kHz or below (A | ±0.1% f.s.) | above 10 kHz) |
| Zero-crossing filter | Off, mild or stror | ng | | | |
| Polarity discrimination | Voltage/current | | ming comparison digital LPF | method | |
| Basic measurement parameters | AC component, v voltage waveform voltage ripple fac rectification RMS fundamental wav -, current total has active power, app current phase an negative-direction magnitude, positi | oltage simple ave peak +, voltage unbai equivalent, curre e component, cu rmonic distortion, arent power, rea gle, power phase n current magnitu ve-direction pow | mean value rectifiin erage, voltage fun waveform peak -, lance factor, RMS ant AC component rrent waveform per current ripple fac ctive power, powe angle, positive-di dde, sum of positiv et magnitude, neg ction power magn | damental wave co voltage total harm current, current m , current simple a ak +, current wav tor, current unbala f factor, voltage p rection current m e- and negative-c ative-direction pc | omponent, nonic distortion, nean value verage, current eform peak ance factor, hase angle agnitude, tirection current wer magnitude, |
| | | m, motor power | slin | | |
| Voltage/current rectification method | | tage and curren | t values to use fo | r calculating ap | parent and |

| | Voltage (U) | Current (I) |
|---|--|---|
| DC | ±0.05% rdg. ±0.07% f.s. | ±0.05% rdg. ±0.07% f.s. |
| $0.5 \text{ Hz} \le f < 30 \text{ Hz}$ | ±0.05% rdg. ±0.1% f.s. | ±0.05% rdg. ±0.1% f.s. |
| | | ±0.05% rdg. ±0.1% f.s. ±0.04% rdg. ±0.05% f.s. |
| 66 Hz < f ≤ 1 kHz | ±0.1% rdg. ±0.1% f.s. | ±0.1% rdg. ±0.1% f.s. |
| 1 kHz < f ≤ 10 kHz | ±0.2% rdg. ±0.1% f.s. | ±0.2% rdg. ±0.1% f.s. |
| 10 kHz < f ≤ 50 kHz | ±0.3% rdg. ±0.2% f.s. | ±0.3% rdg. ±0.2% f.s. |
| | | ±1.0% rdg. ±0.3% f.s. |
| 100 KHZ < I ≤ 200 kl | | ±20% f.s. Phase difference |
| DC | | - |
| 0.5 Hz ≤ f < 30 Hz | ±0.05% rdg. ±0.1% f.s. | ±0.08° |
| 30 Hz ≤ f < 45 Hz | ±0.05% rdg. ±0.1% f.s. | ±0.08° |
| 45 Hz ≤ f ≤ 66 Hz | ±0.04% rdg. ±0.05% f.s. | ±0.08° |
| $66 \text{ Hz} < f \le 1 \text{ kHz}$ | ±0.1% rdg. ±0.1% f.s. | ±0.08° |
| | - | ±(0.06*f+0.02)° ±0.62° |
| | - | ±(0.005*f+0.4)° |
| L | Hz ±20% f.s. | ±(0.022*f-1.3)° |
| | | r Udc and Idc. while accuracy |
| figures for frequencies of | other than DC are defined for Urms | and Irms. |
| | | ed for full-scale input with a |
| | | |
| Accuracy figures for ve | oltage and active power values in | n excess of 220 V in the |
| Accuracy figures for ve | oltage and active power values ir | n excess of 750 V in the |
| frequency range of 30 | kHz to 100 kHz are provided as | reference values. |
| the frequency range of | 100 kHz to 200 kHz are provided a | as reference values. |
| | | excess of 1000 V are |
| Accuracy figures for p | hase difference values outside th | ne frequency range of 45 Hz |
| For voltages in excess | of 600 V, add the following to th | e phase difference accuracy |
| | | |
| 20 kHz < f ≤ 200 kHz | z:±1° | iracy (at 2 V fs) |
| | | |
| | | acy figures for current, activ |
| | | ely for the current |
| | | |
| | | |
| | | Active power (P) |
| DC | | ±0.07% rdg. ±0.077% f.s. |
| 45 Hz ≤ f ≤ 66 Hz | | ±0.06% rdg. ±0.055% f.s. |
| Add ±0.12% f.s. (f.s. = F | PW3390 range) when using 1 A or | 2 A range. |
| high-accuracy 9709-0 | 05, high-accuracy CT6862-05, | or high-accuracy CT6863- |
| | | Active power (P) |
| DC | | ±0.095% rdg. ±0.08% f.s. |
| 45 Hz ≤ f ≤ 66 Hz | ±0.085% rdg. ±0.06% f.s. = | ±0.085% rdg. ±0.06% f.s. |
| | | |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync so zero ground vo adjustment and | cified ranges when the fundame ource, for sine wave input, pow Itage, within effective measure d within the range in which the f | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync si zero ground vo adjustment and the synchronizi | nidity for guaranteed accuracy: n. or more cified ranges when the fundame ource, for sine wave input, pow ltage, within effective measure | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mill Input: Within the spec with the sync si zero ground vo adjustment and the synchronizi ±0.01% f.s./°C (for DC ±0.01% f.s. or less (with | nidity for guaranteed accuracy: n. or more cified ranges when the fundame ource, for sine wave input, pow tlage, within effective measurer by within the range in which the f ation source conditions 2, add ±0.01%s (f.s./°C) th 1000 V @50 Hz/60 Hz applied | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync sr zero ground vo adjustment and the synchronizz ±0.01% f.s./°C (for DC ±0.01% f.s. or less (with measurement jacks ar | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC inpur ment range after zero- undamental wave satisfies between voltage |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync sr zero ground vo adjustment and the synchronizi ±0.01% f.s. or less (wit measurement jacks ar ±1% f.s. or less (in 40 | nidity for guaranteed accuracy: n. or more control of sine wave input, pow tage, within effective measurer y within the range in which the f ation source conditions 2, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and 50 | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the space with the sync sr- adjustment and the synchroniz: ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s. or less (with measurement jacks ar ±1% f.s. or less (in 40 Other than φ = ±90°; | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) h 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (φ+Phase difference a | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) cccuracy//cos(φ)) ×100% rdg |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync si zero ground vo adjustment and the synchroniz; ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s. or less (in 40 Chter than φ = ±90°: ±00s @3 V, current and ac where f.s. active power equa | nidity for guaranteed accuracy: n. or more control of sine wave input, pow tage, within effective measurer y within the range in which the f ation source conditions 2, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and 50 | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(\$) ×100% rdg) ×100% f.s. .s., the current sensor |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync.s zero ground vo adjustment and the synchronizi $\pm 0.01\%$ f.s./7C (for DU $\pm 0.01\%$ f.s./7C (for DU $\pm 0.01\%$ f.s. or less (with measurement jacks ar $\pm 1\%$ f.s. or less (in 40 Other than $\Phi = \pm 90^\circ$: acoos 00 s v. current and ac where f.s. current is t f.s. active power equa current sensor | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer within the range in which the f ation source conditions 2, add 40.01% f.s. ^{p.C}) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a (\$+Phase difference accuracy the power not more than ±6% he rated primary-side current o als the voltage range x the rate | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy)/cos(\$) ×100% rdg > ×100% f.s. .s., the current sensor d primary-side current of the |
| Temperature and hun 80% R.H. or less Warm-up lime: 30 mil Input: Within the space with the sync.s zero ground vo adjustment and the synchronizi $\pm 0.01\%$, f.s./°C (for DU 0.01%, f.s./°C (for DU 0.01%, f.s. or less (wi measurement jacks ar $\pm 1\%$ f.s. or less (in 40 Other than $\phi = \pm 90^\circ$: zcos @3 V, current and ac where f.s. current is th f.s. active power equi current sensor @10 V/m, current and | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer within the range in which the f ation source conditions 2, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 0 A/m magnetic field, DC and f ±(1-cos (φ+Phase difference a c) (φ+Phase difference accuracy tive power not more than ±6% he rated primary-side current o als the voltage range x the rate d active power not more than ±6% | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(op) ×100% rdg) ×100% f.s. .s., the current sensor d primary-side current of the 3% f.s., the current sensor |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spece with the syncs ±0.01% f.s./7C (for DC ±0.01% f.s./7C (for DC ±0.01% f.s./7C (for DC ±0.01% f.s. or less (wil measurement jacks ar ±1% f.s. or less (in 40 Other than $\varphi = \pm 90^{\circ}$: 1000 @3 V, current and ac where f.s. current is t f.s. active power equi where f.s. current sensor @10 V/m, current and where f.s. current sensor | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measured within the range in which the f ation source conditions C, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a :(\$+Phase difference accuracy tive power not more than ±%61 he rated primary-side current o als the voltage range x the rate | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(op) ×100% rdg) ×100% f.s. .s., the current sensor d primary-side current of the 3% f.s., the current sensor |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spece with the sync s zero ground vo adjustment and the synchroniz; $\pm 0.01\%$ f.s./°C (for DC $\pm 0.01\%$ f.s./°C (for DC $\pm 0.01\%$ f.s. or less (in 40 Other than $\phi = \pm 90^{\circ}$; $\pm \cos$ @3 V, current and ac where f.s. current is t f.s. active power equa current sensor @10 V/m, current and h.s. active power equa current sensor | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer within the range in which the f ation source conditions 2, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 0 A/m magnetic field, DC and f ±(1-cos (φ+Phase difference a c) (φ+Phase difference accuracy tive power not more than ±6% he rated primary-side current o als the voltage range x the rate d active power not more than ±6% | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(op) ×100% rdg) ×100% f.s. .s., the current sensor d primary-side current of the 3% f.s., the current sensor |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spece with the syncs ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s. or less (wil measurement jacks ar ±1% f.s. or less (in 40 Other than $\varphi = \pm 90^\circ$: ±000 @3 V, current and ac where f.s. current is t f.s. active power equi current sensor Woltage, Current, Pow | nidity for guaranteed accuracy: n. or more iffed ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and £ ±(1-cos (\$+Phase difference ac- (\$+Phase difference accuracy tive power not more than ±6% i he rated primary-side current o als the voltage range x the rate- ber arated primary-side current o als the voltage range x the rate- site the rated primary-side current o als the voltage range x the rate- | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC inpu- ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(¢)) ×100% rdg) ×100% f.s. s., the current sensor d primary-side current of the 5% f.s., |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync.s zero ground vo adjustment and the synchronizi $\pm 0.01\%$ f.s./7C (for DU $\pm 0.01\%$ f.s./7C (for DU $\pm 0.01\%$ f.s. or less (with measurement jacks ar $\pm 1\%$ f.s. or less (in 40 Other than $\Phi = \pm 90^\circ$: actos 00 3 V, current and ac where f.s. current is t f.s. active power equa current sensor @10 V/m, current and f.s. active power equa current sensor @10 V/m, current and Voltage, Current, Pov Voltage, Current, Pov | nidity for guaranteed accuracy: n. or more iffed ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer attion source conditions 2, add 40.01% f.s. ^{p.C}) th 1000 V @50 Hz/60 Hz applied ad chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a t(\$+Phase difference accuracy the rated primary-side current o als the voltage range x the rate d active power not more than ±6% the rated primary-side current o als the voltage range x the rate ver: 1% to 110% of the range ver: from zero-suppression rang or 0.5% f.s. | 23°C ±3°C (73°F ±5°F), ental wave is synchronized ent factor of one, or DC input ment range after zero- undamental wave satisfies between voltage 50 Hz/60 Hz) ccuracy//cos(\$) ×100% rdg > ×100% f.s. .s., ft he current sensor d primary-side current of the 5% f.s., ft he current sensor d primary-side current of the ge setting to 120% |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spece with the syncs ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s./°C (for DC ±0.01% f.s. or less (wil measurement jacks ar ±1% f.s. or less (in 40 Other than $\varphi = \pm 90^\circ$: acos @3 V, current apo: where f.s. current is t f.s. active power equi current sensor Woltage, Current, Pow Voltage, Current, Pow Selectable CFF, 0.1 c When OFF, non-zero | nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a (\$+Phase difference accuracy tive power not more than ±6% i he rated primary-side current o als the voltage range x the rate d active power not more than ±6% her rated primary-side current o als the voltage range x the rate wer: 1% to 110% of the range wer: 1% to 110% of the range ver 0.5% f.s. values may be displayed even | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(¢)) ×100% rdg) ×100% f.s. s., it he current sensor d primary-side current of the 5% f.s., it he current sensor d primary-side current of the ge setting to 120% with no measurement input |
| Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spece with the sync s zero ground vo adjustment and the synchroniz; ±0.01% f.s./*C (for DC ±0.01% f.s./*C (for DC ±0.01% f.s./*C (for DC ±0.01% f.s./*C (for DC ±0.01% f.s. or less (in 40 Other than $\varphi = \pm 90^\circ$; ±cos @3 V, current and ac where f.s. current is ti f.s. active power equa current sensor Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Zero-adjustr | nidity for guaranteed accuracy: n. or more iffed ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer attion source conditions 2, add 40.01% f.s. ^{p.C}) th 1000 V @50 Hz/60 Hz applied ad chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a t(\$+Phase difference accuracy the rated primary-side current o als the voltage range x the rate d active power not more than ±6% the rated primary-side current o als the voltage range x the rate ver: 1% to 110% of the range ver: from zero-suppression rang or 0.5% f.s. | 23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(\$\$) ×100% rdg) ×100% f.s. .s., the current sensor d primary-side current of the 5% f.s., the current sensor d primary-side current of the ge setting to 120% with no measurement input offset at or below ±10% f.s. |
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| | $\begin{array}{c} 0.5 \mbox{ Hz } \le f < 30 \mbox{ Hz } \le f < 45 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f < 45 \mbox{ Hz } \\ 45 \mbox{ Hz } \le f \le 66 \mbox{ Hz } \\ 11 \mbox{ Hz } \le f \le 66 \mbox{ Hz } \\ 11 \mbox{ Hz } \le f \le 100 \mbox{ Hz } \\ 10 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 60 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 60 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \mbox \mbox{ Hz } Hz $ | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ |

| Measurement mode | Selectable between RMS of | | | |
|---|--|--|--|----------------------------|
| Measurement items | Current integration (Ih+, Ih-, Ih+ and Ih- only for DC mod measurements | and Ih), active po de measurements | ower integration (W s, and Ih only for R | P+, WP-, and WP MS mode |
| Measurement method | Digital calculation from each | | e power phase (whe | n averaging, |
| | calculates with previous aver In DC mode: calculates cur | | rv sample and inte | arates |
| | instantaneous power indep | | | grates |
| | In RMS mode: Integrates curre | | between measurem | ent intervals, and |
| Measurement interval | polarity-independent active po 50 ms data update interval | ower value | | |
| Measuring range | Integration value: 0 Ah/Wh | to +9999.99 TAh | /TWh | |
| | Integration time: No greater | r than 9999h59m | | |
| Integration time accuracy | ±50 ppm ±1 dgt. (0°C to 40 | | | |
| Integration accuracy | ± (current and active power | | | асу |
| Backup function | Integration automatically re | sumes after pow | er outages. | |
| 4. Harmonic Meas | urement Specification | าร | | |
| Number of | 4 channels | | | |
| measurement channels | | | | |
| Measurement items | Harmonic rms voltage, harmo harmonic rms current, harmo | | | |
| | harmonic active power, harm | | | |
| | difference, total harmonic vol | tage distortion, tot | al harmonic current | |
| Measurement method | voltage unbalance factor, cur | | | window) with gon |
| measurement method | Zero-crossing synchronous Fixed 500 kS/s sampling, a | | | with gap |
| | Equal thinning between zer | | | ulation) |
| Harmonic sync source | U1 to U4, I1 to I4, External | | sis and CH B set for | or pulse input), DC |
| FFT calculation word | selectable (50 ms or 100 m 32 bits | IS) | | |
| length | 52 0115 | | | |
| Anti-aliasing filter | Digital filter (automatically s | set based on syn | chronization freque | ency) |
| Windows | Rectangular | | | |
| Synchronization | As specified for power mea | surements | | |
| frequency range | 50 ma (maaauramant fragu | anov denordant | at 45 Hz and halo | |
| Data update interval Phase zero adjustment | 50 ms (measurement-freque Provided by key operation or e | | | |
| THD calculation | THD-F/THD-R | | innana (oni) introve | |
| Highest order analysis | Synchronization | Window | Analysis order | ٦ |
| and window waveforms | frequency range | waveforms | Analysis order | |
| | 0.5 Hz ≤ f < 40 Hz | 1 | 100th | 1 |
| | 40 Hz ≤ f < 80 Hz | 1 | 100th | |
| | 80 Hz ≤ f < 160 Hz | 2 | 80th | |
| | 160 Hz ≤ f < 320 Hz | 4 | 40th | _ |
| | 320 Hz ≤ f < 640 Hz | 8 | 20th | |
| | | | | |
| | 640 Hz ≤ f < 1.2 kHz | 16 | 10th | |
| | | 16 32 | 10th 5th | _ |
| | 640 Hz ≤ f < 1.2 kHz | | | _ |
| Accuracy | 640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz | 32 64 | 5th 3th | wer(P) |
| Accuracy | 640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz | 32 64 Voltage(U), C | 5th 3th urrent(I), Active Po | wer(P) |
| Accuracy | 640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz Frequency | 32 64 | 5th 3th urrent(I), Active Po 0.2% f.s. | wer(P) |
| Accuracy | $640 \text{ Hz} \le f < 1.2 \text{ kHz}$ $1.2 \text{ kHz} \le f < 2.5 \text{ kHz}$ $2.5 \text{ kHz} \le f < 5.0 \text{ kHz}$ Frequency $0.5 \text{ Hz} \le f < 30 \text{ Hz}$ | 32 64 Voltage(U), C ±0.4% rdg. ±0 | 5th 3th urrent(I), Active Po 0.2% f.s. 0.1% f.s. | wer(P) |
| Accuracy | $\begin{array}{l} 640 \mbox{ Hz } \le f < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le f < 2.5 \mbox{ kHz } \\ 2.5 \mbox{ kHz } \le f < 5.0 \mbox{ kHz } \\ \hline \end{tabular}$ | 32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0 | 5th 3th urrent(I), Active Po .2% f.s. 0.1% f.s. 0.2% f.s. | wer(P) |
| Accuracy | $\begin{array}{l} 640 \text{ Hz} \le 1 < 1.2 \text{ kHz} \\ 1.2 \text{ kHz} \le 1 < 2.5 \text{ kHz} \\ 2.5 \text{ kHz} \le 1 < 5.0 \text{ kHz} \\ \hline \\ $ | 32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0 ±0.4% rdg. ±0 | 5th 3th 0.2% f.s. 0.1% f.s. 0.2% f.s. 0.1% f.s. 0.2% f.s. 0.2% f.s. 0.5% f.s. | wer(P) |
| Accuracy | 640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz Frequency 0.5 Hz ≤ f < 30 Hz 30 Hz ≤ f < 400 Hz 400 Hz < f ≤ 1 kHz 1 kHz < f ≤ 5 kHz | 32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0 ±0.4% rdg. ±0 ±1.0% rdg. ±0 | 5th 3th 0.2% f.s. 1.1% f.s. 1.2% f.s. 1.2% f.s. 1.5% f.s. 0.0% f.s. | wer(P) |
| Accuracy | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 2.5 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline \end{tabular}$ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 | Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s. | wer(P) |
| | 640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 2.5 kHz Frequency 0.5 Hz ≤ f < 30 Hz 30 Hz ≤ f < 30 Hz 400 Hz < f ≤ 1 kHz 1 kHz < f ≤ 5 kHz 5 kHz < f ≤ 10 kHz 10 kHz < f ≤ 13 kHz | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 | Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s. | wer(P) |
| 5. Noise Measurer | $\begin{array}{l} 640 \ \text{Hz} \le 1 < 1.2 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 2.5 \ \text{kHz} \le 1 < 5.0 \ \text{kHz} \\ \hline \\ $ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.3% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±2.0% rdg.±1 ±5.0% rdg.±1 | Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s. | wer(P) |
| 5. Noise Measurer Calculation channels Calculation items | $\begin{array}{l} 640 \ \text{Hz} \le 1 < 1.2 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 2.5 \ \text{kHz} \le 1 < 5.0 \ \text{kHz} \\ \hline \end{array}$ | 32 64 Voltage(U), C ±0.4% rdg.±C ±0.4% rdg.±C ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 tencies of 4.3 kH e above when us | Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s. | wwer(P) |
| 5. Noise Measurer Calculation channels Calculation items Calculation type | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \$ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us | Sth 5th 3th | wwer(P) |
| 5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \mbox{ kHz } \\ 1.2 \mbox{ kHz }$ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us | Sth 5th 3th | wer(P) |
| 5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method FFT calculation word | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } kHz $ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us | Sth 5th 3th | wer(P) |
| 5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method FFT calculation word length FFT data points | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \$ | 32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 uencies of 4.3 kH e above when us CH4) e (according to disp | 5th 5th 3th urrent(I), Active Po 1.2% f.s. 1.2% f.s. 5% f.s. 0.0% f.s. 0.0% f.s. 2 and higher ing LPF. | ecording length) |
| 5. Noise Measurer | $\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \\ \hline 3.$ | 32 64 Voltage(U), C ±0.4% rdg.±C ±0.4% rdg.±C ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 (according to 4.3 kH e above when us CH4) e (according to disp as with maximum | 5th 5th 3th urrent(I), Active Po 1.2% f.s. 1.2% f.s. 5% f.s. 0.0% f.s. 0.0% f.s. 2 and higher ing LPF. | ecording length) |

 Data update interval
 Determined by FFT points within approx. 400 ms, 1 s, 2 s, or 15 s, with gap

 Highest analysis frequency
 100 kHz/50 kHz/20 kHz/10 kHz/5 kHz/2 kHz

 Frequency resolution
 0.2 Hz to 500 Hz (Determined by FFT points and maximum analysis frequency)

 Noise amplitude measurement Lower limit noise frequency
 Calculates the ten highest level and frequency voltage and current FFT peak values (local maxima).

 Lower limit noise frequency
 0 kHz to 10 kHz

-6. Motor Analysis Specifications (Model PW3390-03)

| Number of input channels | 3 channels CH A: Analog DC input/Frequency input (selectable) CH B: Analog DC input/Pulse input (selectable) CH Z: Pulse input |
|------------------------------------|--|
| Measurement input terminal type | Insulated BNC jacks |
| Input impedance (DC) | 1 MΩ ±100 kΩ |
| Input methods | Isolated and differential inputs (not isolated between channels B and Z) |
| Measurement items | Voltage, torque, rotation rate, frequency, slip, and motor power |
| Synchronization source | U1 to U4, I1 to I4, Ext (with CH B set for pulse input), DC (50 ms/100 ms) Common to channels A and B |
| Measurement frequency source | f1 to f4 (for slip calculations) |
| Maximum input voltage | ±20 V (during analog, frequency, and pulse input) |
| Maximum rated voltage to earth | 50 V (50 Hz/60 Hz) |
| (1). Analog DC Inpu | ut (CH A/CH B) |
| Measurement range | ±1 V, ±5 V, ±10 V (when inputting analog DC) |
| Valid input range | 1% to 110% f.s. |
| Sampling | 10 kHz/16 bits |
| Response time | 1 ms (measuring zero to full scale, with LPF off) |
| Measurement method | Simultaneous digital sampling and zero-crossing synchronous calculation system (cumulative average of intervals between zero crossings) |
| | (culturative average of intervals between zero crossings) |

| Temperature coefficient | ±0.03% f.s./°C |
|---|---|
| Effect of common mode voltage | Not more than ±0.01% f.s. (with 50 V [DC or 50 Hz/60 Hz] between measurement jacks and PW3390 |
| Effect of external | chassis) Not more than ±0.1% f.s. (at 400 A/m DC and 50 Hz/60 Hz magnetic fields) |
| magnetic field LPF | OFF/ON (OFF: 4 kHz, ON: 1 kHz) |
| Total display area | Zero-suppression range setting ±120% |
| Zero adjustment | Zero-corrected input offset of voltage ±10% f.s. or less |
| Scaling | 0.01 ~ 9999.99 |
| Unit | CH A: V, N• m, mN• m, kN• m CH B: V, Hz, r/min |
| 2). Frequency Inpu | ut (CH A only) |
| Valid amplitude range Max. measurement | ±5 V peak (5 V symmetrical, equivalent to RS-422 complementary signal) 100 kHz |
| frequency Moscurement range | 1 kHz to 100 kHz |
| Measurement range Data output interval | According to synchronization source |
| Measurement accuracy | |
| Total display area | 1.000 kHz to 99.999 kHz |
| Frequency range | Select fc and fd for frequency range fc \pm fd [Hz] (frequency measurement only 1 kHz to 98 kHz in 1 kHz units, where fc + fd < 100 kHz and fc - fd > 1 kHz |
| Rated torque | 1 ~ 999 |
| Unit | Hz, N• m, mN• m, kN• m |
| 3). Pulse Input (CH | |
| Detection level | Low: 0.5 V or less; High: 2.0 V or more |
| Measurement range Division setting range | 1 Hz to 200 kHz (at 50% duty) 1 ~ 60000 |
| Division setting range Measurement | 0.5 Hz to 5.0 kHz (limited to measured pulse frequency divided by selected not |
| frequency range Minimum detectable | $2.5 \mu s$ or more |
| pulse width | 2.5 µ3 01 11010 |
| Measurement accuracy | |
| Motor poles Max. measurement | 2 ~ 98 100 Hz, 500 Hz, 1 kHz, 5 kHz |
| frequency | |
| Pulse count | Integer multiple of half the number of motor poles, from 1 to 60,000 |
| Unit | Hz, r/min |
| 4). Pulse Input (CH | |
| Detection level Measurement range | Low: 0.5 V or less; High: 2.0 V or more 0.1 Hz to 200 kHz (at 50% duty) |
| Minimum detectable | 2.5 µs or more |
| pulse width | OEE/Z Bhase/R Bhase (clear counts of CHR in riging odge during Z Bhase |
| Settings | OFF/Z Phase/B Phase (clear counts of CHB in rising edge during Z Phase, detect polar code for number of rotations during B Phase) |
| 7. D/A Output Opti | on Specifications (Models PW3390-02 and PW3390-03) |
| Number of output | 16 channels |
| channels Output contents | CH1 to CH8: Selectable analog/waveform outputs |
| | CH9 to CH16: Analog output |
| Output items | Analog output: Select a basic measurement item for each output channel. Waveform output: Output voltage or current measured waveforms. |
| Output connector | One 25-pin female D-sub |
| D/A conversion resolution | 16 bits (polarity + 15 bits) |
| Output accuracy | Analog output: Measurement accuracy ±0.2% f.s. (DC level) |
| | Waveform output: Measurement accuracy ±0.5% f.s. (at ±2 V f.s.), ±1.0% f.s. (at ±1 V f.s.) |
| | (rms level within synchronous frequency range) |
| Output update interval | Analog output: 50 ms (according to input data update interval of selected parameter Waveform output: 500 kHz |
| Output voltage | Analog output: ±5 V DC nom. (approx. ±12 V DC max.) Waveform output: ±2 V/±1 V switchable, crest factor of 2.5 or greater |
| Output impedance | Setting applies to all channels. 100 Ω ±5 Ω |
| Temperature coefficient | ±0.05% f.s./°C |
| ·8. Display Specific | Leations |
| Display type | 9-inch TFT color LCD (800×480 dots) |
| Display refresh interval | Measurement values: 200 ms (independent of internal data update interval) |
| | Waveforms, FFT: screen-dependent |
| 9. External Interface (| |
| Connector | Mini-B receptacle ×1 |
| Compliance standard | USB2.0 (Full Speed/High Speed) |
| Class | Individual (USB488h) |
| Connection destination Function | Computer (Windows10/Windows8/Windows7, 32bit/64bit) Data transfer and command control |
| 2). USB Memory Ir | |
| Connector | USB type A connector ×1 |
| Compliance standard | USB2.0 |
| USB power supply | 500 mA maximum |
| USB storage device support | USB Mass Storage Class |
| Function | Save and load settings files, Save waveform data |
| | Save displayed measurement values (CSV format) Copy measurement values and recorded data (from CF card) |
| | Save screen captures |
| 3). LAN Interface | |
| | RJ-45 connector x 1 |
| (3). LAN Interface Connector Compliance standard | IEEE 802.3 compliant |
| Connector Compliance standard Transmission method | IEEE 802.3 compliant 10BASE-T/100BASE-TX Auto detected |
| Connector Compliance standard | IEEE 802.3 compliant |

| Slot | One Type 1 |
|------------------------------|---|
| Compatible card | CompactFlash memory card (32 MB or higher) |
| Supported memory capacity | Up to 2 GB |
| Data format | MS-DOS format (FAT16/FAT32) |
| Recordable content | Save and load settings files, Save waveform data Save displayed measurement values and auto-recorded data (CSV format, Copy measurements/recorded data (from USB storage) Save screen captures |
| (5). RS-232C Interf | ace |
| Method | RS-232C, [EIA RS-232D], [CCITT V.24], [JIS X5101] compliant Full duplex, start-stop synchronization, 8-bit data, no parity, one stop bit Hardware flow control, CR+LF delimiter |
| Connector | D-sub9 pin connector ×1 |
| Communication speeds | 9600 bps, 19,200 bps, 38,400 bps |
| Function | Command control, Bluetooth® logger connectivity (simultaneous use not supported) |
| (6). Synchronization | n Control Interface |
| Signal contents | One-second clock, integration START/STOP, DATA RESET, EVENT |
| Connector types | IN: One 9-pin female mini-DIN jack, OUT: One 8-pin female mini-DIN jack |
| Signal | 5 V CMOS |
| Max. input | ±20 V |
| Max. signal delay | 2 μs (rising edge) |
| (7). External Contro | bl Interface |
| Connector types | 9-pin round connector x1; also used as synchronization control interface |
| Electrical specifications | Logic signal of 0 V/5 V (2.5 V to 5 V), or contact signal (shorted/open) |
| Function | Integration start integration stop, data reset, event (the event set as the |

| Signal | 5 V CMOS |
|---------------------------|--|
| Max. input | ±20 V |
| Max. signal delay | 2 µs (rising edge) |
| (7). External Contro | ol Interface |
| Connector types | 9-pin round connector ×1; also used as synchronization control interface |
| Electrical specifications | Logic signal of 0 V/5 V (2.5 V to 5 V), or contact signal (shorted/open) |
| Function | Integration start, integration stop, data reset, event (the event set as the synchronization control function) Cannot be used at the same time as synchronization control. |

Function Specifications

| AUTO range function | Automatically selects voltage and current ranges according to measured ampli- |
|------------------------------|---|
| Ao to tange function | tude on each phase. |
| | Operating states: Selectable on or off for each phase system |
| | Auto-ranging span: Wide/Narrow (common to all wiring systems) |
| Timing control function | Interval OFF/50 ms/100 ms/200 ms/500 ms/1 s/5 s/10 s/ |
| | 15 s/30 s/1 min/5 min/10 min/15 min/30 min/60 min |
| | Setting determines the maximum data-saving capacity |
| | Timing controls OFF/Timer/BTC |
| | Timer : 10 s to 9999:59:59 [h:m:s] (in seconds) |
| | Real-time clock : Start and stop times (in minutes) |
| Hold function | Stops all updating of displayed measurement values and waveforms, and holds |
| | display. |
| | Internal calculations such as integration and averaging, clock, and peak-over display continue to be updated. |
| Peak hold function | All measurement values are updated to display the maximum value for each |
| | measurement. |
| | Displayed waveforms and integration values continue to be updated with instan- taneous values. |
| 2. Calculation Fun | ctions |
| Scaling calculation | VT(PT) ratio and CT ratio: OFF/0.01 to 9999.99 |
| Average calculation | OFF/FAST/MID/SLOW/SLOW2/SLOW3 |
| | Exponentially averages all instantaneous measurement values including |
| | harmonics (but not peak, integration, or FFT noise values). Applied to displayed values and saved data. |
| | Response speed (time remains within specified accuracy when input changes |
| | from 0 to 100% f.s.) |
| | FAST: 0.2 s, MID: 1.0 s, SLOW: 5 s, SLOW2: 25 s, SLOW3: 100 s |
| Efficiency and loss | Efficiency η [%] and Loss [W] are calculated from active power values measured |
| calculations | on each phase and system. For PW3390-03, motor power (Pm) is also applied as a calculation item. |
| | Maximum no. of simultaneous calculations: Efficiency and loss, by three |
| | formulas (Parameters are specified for Pin and Pout) |
| | Calculation method: Efficiency η = 100 × IPoutI/IPinI Loss = IPinI - IPoutI |
| ∆-Y calculation | For 3P3W3M systems, converts between line-to-line voltage and phase voltage |
| | waveforms using a virtual center point. |
| | All voltage parameters including harmonics such as true rms voltage are calculated as |
| | phase voltage waveforms. U1s = (U1s-U3s)/3, U2s = (U2s-U1s)/3, U3s =(U3s-U2s)/3 |
| Selecting the | TYPE1/TYPE2 (only valid when wiring is 3P3W3M) |
| calculation method | Select the calculation method used to calculate the apparent power and reactive |
| | power during 3P3W3M wiring. |
| Current sensor phase | Only affect measurement values S123, Q123, φ123, λ123 |
| correction calculations | Compensation by calculating the current sensor's harmonic phase characteristics Correction points are set using frequency and phase difference (set separately |
| | for each wiring mode). |
| | Frequency: 0.001 kHz to 999.999 kHz (in 0.001 kHz increments) |
| | Phase difference: 0.00 deg. to ±90.00 deg. (in 0.01 deg. increments) However, the time difference calculated from the frequency phase difference is |
| | limited to a maximum of 200 us in 5 ns increments. |
| 3. Display Functio | ns |
| Wiring Check screen | The wiring diagram and voltage/current vectors are displayed for the selected |
| | wiring system(s). |
| | The correct range for the wiring system is shown on the vector display, to confirm proper measurement cable connections. |
| Independent wiring | Displays power and harmonic measurement values for channels 1 to 4. |
| system display mode | A composite measurement line pattern is displayed for each system. |
| | Basic, voltage, current, and power measurement parameter, |
| Display Calastian | harmonic bar graph, harmonic list, and harmonic vector screens |
| Display Selections screen | Select to display any 4, 8, 16, or 32 of the basic measurement parameters. Display layout: 4, 8, 16, or 32 parameters (4 patterns) |
| | |
| Efficiency and Loss screen | The efficiency and loss obtained by the specified calculation formulas are displayed numerically. Three efficiency and three loss values. |

| Waveform & Noise screen | Voltage and current waveforms sampled at 500 kHz and noise measurements are displayed compressed on one screen. Trigger: Synchronized with the harmonic sync source Recording length: 1000/5000/10,000/50,000 x All voltage and current channels Compression ratio: 1/1, 1/2, 1/5, 1/10, 1/20, 1/50 (peak-to-peak compression) Recording time: | | | | |
|--|--|---|--|--|---------------------------------|
| | Recording speed/ Recording length | 1000 | 5000 | 10,000 | 50,000 |
| | 500 kS/s | 2 ms | 10 ms | 20 ms | 100 ms |
| | 250 kS/s 100 kS/s | 4 ms 10 ms | 20 ms 50 ms | 40 ms 100 ms | 200 ms 500 ms |
| | 50 kS/s | 20 ms | 100 ms | 200 ms | 1000 ms |
| | 25 kS/s | 40 ms | 200 ms | 400 ms | 2000 ms |
| | 10 kS/s | 100 ms | 500 ms | 1000 ms | 5000 ms |
| X-Y Plot screen | Select horizontal and vertical axes from the basic measurement items to displa on the X-Y graphs. Dots are plotted at the data update interval, and are not saved. Drawing data can be cleared. Horizontal: 1 data item (gauge display available), Vertical: 2 data items (gauge display available) | | | | |
| -4. Saving Function | | | | | |
| Auto-save function | As the items to be saw noise value data of the during every measure Can be controlled by t Max. no. of saved item Data format: CSV form | e FFT function ment interval. imer or real-tir ns: Interval-set | . The selected (Storage to U ne clock. | d items are sto SB memory is | ored to CF ca |
| Manual saving function | | | card | | |
| | Measurement data As the items to be and noise value da Pressing the SAVI the save destination File format: CSV fc Screen capture The COPY key can destination. "This function can saving is in progre File format: Comp Settings data Settings data Settings data Settings data Saves the wavefor File format: CSV fc | ta of the FFT E key saves ea on. ormat botures and sav be used at an ss. ressed BMP fc on can be save ormat (for PW3 m being displa | function. Ich measuren res a bitmap in interval of 5 s prmat ed/loaded as a 3390 only) | nent value at th mage of the di sec or more wi a settings file. | hat moment to splay to the s |
| -5. Synchronous C | | Jinat | | | |
| Function | Synchronous measure Model PW3390 (mast When internal settings | er/slave). | | | |
| Synchronized items | Clock, data update int | erval (except f | | | |
| Event items | data reset, certain events Hold, manual save, screen capture | | | | |
| Synchronization timing | Clock, data update ir Within 10 s after p Start/stop, data rese | nterval ower-on by a s | ave PW3390 | I | |
| Synchronization delay | Upon key-press ar Maximum 5 µs per con | | | | |
| -6. Bluetooth [®] Log | | lection. Maxim | un synchioniz | alloir delay or a | |
| Function | Sends measured valu | es wirelessly t | o logger by us | ing a Bluetoo | th® serial |
| | | conversion adapter. | | | |
| Supported devices | Hioki LR8410 Link-compatible loggers (LR8410, LR8416) Measured values assigned to the D/A CH9 to CH16 analog output parameters | | | | |
| | | | | | out parameter |
| Supported devices | Measured values assi | | | | out parameter |
| Supported devices Sent data -7. Other Functions Display language selection | Measured values assi | gned to the D/ | | | out parameter |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound | Measured values assi Japanese, English, Cl OFF/ON | gned to the D/ ninese | A CH9 to CH1 | 6 analog outp | out parameter |
| Supported devices Sent data -7. Other Functions Display language selection | Measured values assi | gned to the D/ ninese ue-green)/3 (b | A CH9 to CH1 | 6 analog outp | out parameter |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight | Measured values assi Japanese, English, Cł OFF/ON COLOR1 (black)/2 (bli Wiring or Last-display ON/1 min/5 min/10 mi | gned to the D/ ninese ue-green)/3 (b ed screen (Me | A CH9 to CH1 lue)/4 (gray)/5 | 6 analog outp | ut parameter |
| Supported devices Sent data 7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV | gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m | A CH9 to CH1 lue)/4 (gray)/5 asurement so | 6 analog outp | ut parameter |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Beal-time clock function | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-y | gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting | A CH9 to CH1 lue)/4 (gray)/5 asurement so | 6 analog outp | ut parameter |
| Supported devices Sent data 7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-y ±3 s per day @25°C (Current sensors are a | gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re | A CH9 to CH1 lue)/4 (gray)/5 rasurement so in 24-hour clock | 6 analog outp i (navy blue) reens only) | |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yi ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete | gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re s) rs on voltage a coted | A CH9 to CH1 lue)/4 (gray)/5 assurement so in 24-hour clock accognized who and current m | 6 analog out; (navy blue) reens only) an connected pasurement cl | (Excluding th |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy Sensor recognition Warning indicators Key-lock | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yr ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete Warning indicators for Toggles on/off by hold | gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re 's) rs on voltage a cted all channels ai ing the ESC k | A CH9 to CH1 lue)/4 (gray)/5 assurement sc in 24-hour clock and current m re displayed o ey for three sc | 6 analog outp (navy blue) (reens only) en connected assurement ct n all pages of t | (Excluding th |
| Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy Sensor recognition Warning indicators | Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yr ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete Warning indicators for | gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) uutomatically re s) rs on voltage a beted all channels al ing the ESC k factory defaul | A CH9 to CH1 lue)/4 (gray)/5 assurement so in 24-hour clock ecognized wh and current m re displayed o y for three so ts | 6 analog out; (navy blue) (navy blue) (na | (Excluding th hannels, Whe |

General Specifications

| Operating environment Indoors, Pollution Degree 2, altitude up to 2000 m (6562.20 ft) Operating temperature Temperature: 0° to 40°C (32°F to 104°F), Humidity: 80% RH or less and humidity (no condensation) Storage temperature and humidity -10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation) Dustproof and waterproof IP30 (EN 60529) (With CF card cover open: IP20) Applicable standards Safety EN 61010 EMC Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m (2.95 tt)) ×1, Input cord label ×2, D-sub connector ×1 (PW3390-02, PW3390-03) | | | |
|--|--------------------------|--|--|
| and humidity (no condensation) Storage temperature and humidity -10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation) Dustproof and waterproof IP30 (EN 60529) (With CF card cover open: IP20) Applicable standards Safety EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithum battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Operating environment | Indoors, Pollution Degree 2, altitude up to 2000 m (6562.20 ft) | |
| and humidity Image: Constraint of the second s | | | |
| Applicable standards Safety EN 61010 EMC EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | | -10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation) | |
| EMC EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Dustproof and waterproof | IP30 (EN 60529) (With CF card cover open: IP20) | |
| Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Applicable standards | | |
| Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Power supply | | |
| Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Backup battery life | Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) | |
| Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Dimensions | 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) | |
| Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m | Mass | 4.6 kg (162.3 oz) with PW3390-03 | |
| | Product warranty period | 1 year | |
| | Accessories | | |

High Accuracy Sensor, Pass-Through Type

| | AC/DC CURRENT SENSOR CT6862-05 | AC/DC CURRENT SENSOR CT6863-05 | AC/DC CURRENT SENSOR 9709-05 | AC/DC CURRENT SENSOR CT6865-05 |
|---|--|---|--|--|
| External Appearance | | | | |
| Rated primary current | AC/DC 50 A rms | AC/DC 200 A rms | AC/DC 500 A rms | AC/DC 1000 A rms |
| Frequency band | DC to 1 MHz | DC to 500 kHz | DC to 100 kHz | DC to 20 kHz |
| Diameter of measurable conductors | φ 24 mm (0.94 in) or less | φ 24 mm (0.94 in) or less | φ 36 mm (1.42 in) or less | φ 36 mm (1.42 in) or less |
| Basic accuracy | For DC, 16 Hz to 400 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications | For DC, 16 Hz to 400 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications | For DC, 45 Hz to 66 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications | For DC, 16 Hz to 66 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications |
| Frequency characteristics (Amplitude) | to 100 kHz: ±2.0% rdg. ±0.05% f.s. | to 16 Hz: ±0.1% rdg. ±0.02% f.s. 400 Hz to 1 kHz: ±0.2% rdg. ±0.02% f.s. to 10 kHz: ±1.0% rdg. ±0.02% f.s. to 100 kHz: ±5.0% rdg. ±0.05% f.s. to 500 kHz: ±30% rdg. ±0.05% f.s. | to 45 Hz: ±0.2% rdg. ±0.02% f.s. 66 Hz to 500 Hz: ±0.2% rdg. ±0.02% f.s. to 5 kHz: ±0.5% rdg. ±0.05% f.s. to 10 kHz: ±2.0% rdg. ±0.05% f.s. to 10 kHz: ±2.0% rdg. ±0.05% f.s. to 10 kHz: ±3.0% rdg. ±0.10% f.s. | to 16 Hz: ±0.1% rdg, ±0.02% f.s. 66 Hz to 100 Hz: ±0.5% rdg, ±0.02% f.s. to 500 Hz: ±1.0% rdg, ±0.02% f.s. to 5 KHz: ±0.0% rdg, ±0.05% f.s. to 20 kHz: ±30% rdg, ±0.01% f.s. |
| Operating temperature range | -30°C to 85°C (-22°F to 185°F) | -30°C to 85°C (-22°F to 185°F) | 0°C to 50°C (32°F to 122°F) | -30°C to 85°C (-22°F to 185°F) |
| Effect of conductor position | ±0.01% rdg. or less (DC to 100 Hz) | ±0.01% rdg. or less (DC to 100 Hz) | ±0.05% rdg. or less (DC) | ±0.05% rdg. or less (50/60 Hz) |
| Effects of external magnetic fields | In 400 A/m magnetic field (DC and 60 Hz) 10 mA or less | In 400 A/m magnetic field (DC and 60 Hz) 50 mA or less | In 400 A/m magnetic field (DC and 60 Hz) 50 mA or less | In 400 A/m magnetic field (DC and 60 Hz) 200 mA or less |
| Maximum rated voltage to ground | CAT III 1000 V | CAT III 1000 V | CAT III 1000 V | CAT III 1000 V |
| Output connector | HIOKI ME15W | HIOKI ME15W | HIOKI ME15W | HIOKI ME15W |
| Dimensions | 70 mm (2.76 in) W x 100 mm (3.94 in) H x 53 mm (2.09 in) D, Cable length: 3 m (9.84 ft) | 70 mm (2.76 in) W x 100 mm (3.94 in) H x 53 mm (2.09 in) D, Cable length: 3 m (9.84 ft) | 160 mm (6.30 in) W x 112 mm (4.41 in) H x 50 mm (1.97 in) D, Cable length: 3 m (9.84 ft) | 160 mm (6.30 in) W x 112 mm (4.41 in) H x 50 mm (1.97 in) D, Cable length: 3 m (9.84 ft) |
| Mass | Approx. 340 g (12.0 oz) | Approx. 350 g (12.3 oz) | Approx. 850 g (30.0 oz) | Approx. 980 g (34.6 oz) |
| Derating Characteristics | B00 H 80 B 00 D C 1 10 100 1k 10k 10k 1M Frequency [H2] | E 400 B 300 B 200 D C 1 10 100 1k 10k 100 k1 M Frequency [tz] | 2000 200 2000 2 | Terupon Ter |

Custom cable lengths also available. Please inquire with your Hioki distributor.

High Accuracy Sensor, Clamp Type

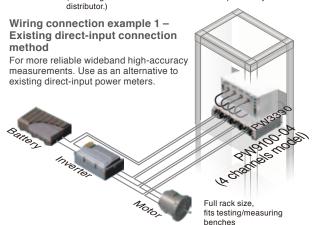
| | AC/DC CURRENT PROBE CT6841-05 | AC/DC CURRENT PROBE CT6843-05 | AC/DC CURRENT PROBE CT6844-05 | AC/DC CURRENT PROBE CT6845-05 | AC/DC CURRENT PROBE CT6846-05 | |
|---|---|---|--|--|--|--|
| External Appearance | | | | | | |
| Rated primary current | AC/DC 20 A rms | AC/DC 200 A rms | AC/DC 500 A rms | AC/DC 500 A rms | AC/DC 1000 A rms | |
| Frequency band | DC to 1 MHz | DC to 500 kHz | DC to 200 kHz | DC to 100 kHz | DC to 20 kHz | |
| Diameter of measurable conductors | φ 20 mm (0.79 in) or less (insulated conductor) | φ 20 mm (0.79 in) or less (insulated conductor) | φ 20 mm (0.79 in) or less (insulated conductor) | φ 50 mm (1.97 in) or less (insulated conductor) | φ 50 mm (1.97 in) or less (insulated conductor) | |
| Basic accuracy | For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.05\%$ f.s. | For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s. | For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s. | For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s. | For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s. | |
| Frequency characteristics (Amplitude) | to 10 kHz: ±1.5% rdg. ±0.02% f.s. | to 500 Hz: ±0.3% rdg. ±0.02% f.s. to 1 kHz: ±0.5% rdg. ±0.02% f.s. to 10 kHz: ±1.5% rdg. ±0.02% f.s. to 50 kHz: ±5.0% rdg. ±0.02% f.s. to 50 kHz: ±30% rdg. ±0.05% f.s. | $\begin{array}{llllllllllllllllllllllllllllllllllll$ | to 1 kHz: ±0.5% rdg. ±0.02% f.s. | to 500 Hz: ±0.5% rdg. ±0.02% f.s. to 1 kHz: ±1.0% rdg. ±0.02% f.s. to 5 kHz: ±2.0% rdg. ±0.02% f.s. to 10 kHz: ±5.0% rdg. ±0.05% f.s. to 20 kHz: ±30% rdg. ±0.10% f.s. | |
| Operating temperature range | -40°C to 85°C (-40°F to 185°F) | -40°C to 85°C (-40°F to 185°F) | -40°C to 85°C (-40°F to 185°F) | -40°C to 85°C (-40°F to 185°F) | -40°C to 85°C (-40°F to 185°F) | |
| Effect of conductor position | ±0.1% rdg. or less (DC to 100 Hz) | ±0.1% rdg. or less (DC to 100 Hz) | ±0.1% rdg. or less (DC to 100 Hz) | ±0.2% rdg. or less (DC to 100 Hz) | ±0.2% rdg. or less (50 Hz/60 Hz) | |
| Effects of external magnetic fields | In 400 A/m magnetic field (DC and 60 Hz) under 50 mA | In 400 A/m magnetic field (DC and 60 Hz) under 50 mA | In 400 A/m magnetic field (DC and 60 Hz) under 100 mA | In 400 A/m magnetic field (DC and 60 Hz) under 150 mA | In 400 A/m magnetic field (DC and 60 Hz) under 150 mA | |
| Output connector | HIOKI ME15W | HIOKI ME15W | HIOKI ME15W | HIOKI ME15W | HIOKI ME15W | |
| Dimensions | 153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft) | 153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft) | 153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft) | 238 mm (9.37 in) W x 116 mm (4.57 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft) | 238 mm (9.37 in) W x 116 mm (4.57 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft) | |
| Mass | 350 g (12.3 oz) | 370 g (13.1 oz) | 400 g (14.1 oz) | 860 g (30.3 oz) | 990 g (34.9 oz) | |
| Derating Characteristics | Tic Ambient temperature -40°C (-40°F) < TA < 60°C (140°F) -40°C (-40°F) < TA < 60°C (140°F) < TA < 60°C | Tr. Ambient temperature -40°C (-40°F) = TA ≤ 40°C (-104°F) -40°C (-104°F) = TA ≤ 40°C (-104°F) -40°C (-104°F) = TA ≤ 60°C (-104°F) -40°C (-40°F) = TA ≤ 80°C (-104°F) -40°C (-40°F) = TA ≤ 80°C (-105°F) -40°C (-40°F) = TA ≤ 40°C (-105°F) -40°C (-105°F) = TA ≤ 40°C (-105°F) = TA ≤ 40°C (-105°F) -40°C (-105°F) = TA ≤ 40°C (-105°F) | 500 500 100 100 100 100 100 100 | Th: Ambient temperature Th: Ambient temperatu | | |

Custom cable lengths also available. Please inquire with your Hioki distributor.

High Accuracy Sensor, Direct Wire Type

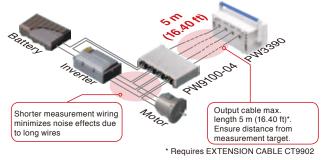
| | AC/DC CURRENT BOX PW9100-03 | AC/DC CURRENT BOX PW9100-04 | |
|---|--|--|--|
| External Appearance | in in in | in in in in | |
| Number of input channels | 3ch | 4ch | |
| Rated primary current | AC/DC | 50 A rms | |
| Frequency band | DC to 3.5 M | MHz (-3 dB) | |
| Measurement terminals | Terminal block (with sa | afety cover), M6 screws | |
| Basic accuracy | For 45 Hz to 65 Hz Amplitude: ±0.02% rdg. ±0.005% f.s. For DC Amplitude: ±0.02% rdg. ±0.007% f.s. | | |
| Frequency characteristics (Amplitude) | to 1 kHz: ±0.1% to 50 kHz: ±1% r to 100 kHz: ±2% i to 1 MHz: ±10% | 6 rdg. ±0.02% f.s. 6 rdg. ±0.01% f.s. dg. ±0.02% f.s. rdg. ±0.05% f.s. rdg. ±0.05% f.s. Typical | |
| Input resistance | 1.5 mΩ or less | s (50 Hz/60 Hz) | |
| Operating temperature range | 0°C to 40°C (32°F to 104°F) | | |
| Effects of common- mode voltage (CMRR) | | er 100 kHz 120 dB or greater e/common-mode voltage) | |
| Maximum rated voltage to ground | 1000 V (Measurement category II), | , 600 V (Measurement category III), t overvoltage 6000 V | |
| Output connector | HIOKI | ME15W | |
| Dimensions | | 3.46 in) H x 260 mm (10.24 in) D, 0.8 m (2.62 ft) | |
| Mass | 3.7 kg (130.5 oz) | 4.3 kg (151.7 oz) | |
| Derating Characteristics | The second secon | | |

Newly developed DCCT method allows world-class measurement range and measurement accuracy at a rating of 50 A. (5 A rating version also available. Please inquire with your Hioki



Wiring connection example 2 - Introducing a new and innovative measuring method

Shorten the wiring for current measurement by installing the PW9100 close to the measurement target. This will also keep the effects of wiring resistance, capacity coupling and other objective factors on the measured values to a minimum.



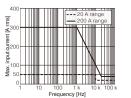
CLAMP ON SENSOR 9272-05 AC 200 A rms/20 A rms switching 1 kHz to 100 kHz φ 46 mm (1.81 in) or less For 45 Hz to 66 Hz Amplitude: ±0.3% rdg. ±0.01% f.s. Phase:±0.2 ° ±2.0% rdg. ±0.10% f.s. ±0.5% rdg. ±0.02% f.s. ±2.5% rdg. ±0.02% f.s. ±5% rdg. ±0.1% f.s. ±30% rdg. ±0.1% f.s. to 10 Hz: to 45 Hz: 66to 10 kHz: to 50 kHz to 100 kHz:

0°C to 50°C (32°F to 122°F) ±0.2% rdg. or less (60 Hz)

In 400 A/m magnetic field (60 Hz) under 100 mA

HIOKI ME15W

78 mm (3.07 in) W x 188 mm (7.40 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft) 450 g (15.9 oz)



Standard Sensor

| | AC/DC CURRENT SENSOR CT7642 AC/DC AUTO ZERO CURRENT SENSOR CT7742 | AC FLEXIBLE CURRENT SENSOR CT7044, CT7045, CT7046 | |
|---|--|---|--|
| External Appearance | | | |
| Rated primary current | AC/DC 2000 A rms | AC 6000 A rms | |
| Frequency band | CT7642: DC to 10 kHz CT7742: DC to 5 kHz | 10 Hz to 50 kHz (±3 dB) | |
| Diameter of measurable conductors | φ 55 mm (2.17 in) or less | CT7044: φ 100 mm (3.94 in) or less CT7045: φ 180 mm (7.09 in) or less CT7046: φ 254 mm (10.00 in) or less | |
| Basic accuracy | For DC, 45 Hz to 66 Hz Amplitude: ±1.5% rdg. ±0.5% f.s. For up to 66 Hz Phase:±2.3 ° | For 45 to 66 Hz, with flexible cable core Amplitude: ±1.5% rdg. ±0.25% f.s. Phase:±1.0 ° | |
| Frequency characteristics (Amplitude) | 66 kHz to 1 kHz ±2.5% rdg. ±1.0% f.s. | - | |
| Operating temperature range | -25°C to 65°C (-13°F to 149°F) | -25°C to 65°C (-13°F to 149°F) | |
| Effect of conductor position | ±1.0% rdg. or less | ±3.0% or less | |
| Effects of external magnetic fields | In 400 A/m magnetic field (DC) 0.2% f.s. or less | In 400 A/m magnetic field (50 Hz/60 Hz) CT7044, CT7045: 1.25% f.s. or less CT7046: 1.5% f.s. or less | |
| Output connector | HIOKI PL14* | HIOKI PL14* | |
| Dimensions | 64 mm (2.52 in) W x 195 mm (7.68 in) H x 34 mm (1.34 in) D Cable length: 2.5 m (8.20 ft) | Circuit box: 25 mm (0.98 in) W x 72 mm (2.83 in) H x 20 mm (0.79 in) D Cable length: 2.5 m (8.20 ft) | |
| Mass | 510 g (18.0 oz) | CT7044: 160 g (5.6 oz) CT7045: 174 g (6.1 oz) CT7046: 186 g (6.6 oz) | |
| Derating Characteristics | 2.5 k 2.5 k 2. | 12 k 12 k 10 k 6 k 0 k 0 k 10 | |

Current Summing

| | SENSOR UNIT CT9557 | |
|---------------------------------|---|--|
| | FRONT | |
| External Appearance | Sensor input | |
| | REAR | |
| | Summed waveform output (CT9904 connected) | |
| Connectable current sensor | Current sensor with HIOKI ME15W (male) on the output connector | |
| Summed waveform output accuracy | DC: ±0.06% rdg.±0.03% f.s. to 1 kHz: ±0.06% rdg.±0.03% f.s. to 10 kHz: ±0.10% rdg.±0.03% f.s. to 10 kHz: ±0.20% rdg.±0.10% f.s. to 100 kHz: ±0.20% rdg.±0.10% f.s. to 300 kHz: ±1.0% rdg.±0.20% rdg.t.s. to 700 kHz: ±5.0% rdg.±0.20% f.s. to 11 MHz: ±10.% rdg.±0.50% f.s. | |
| Operating temperature range | -10°C to 50°C (14°F to 122°F) | |
| Power supply | AC ADAPTER Z1002 (100 to 240 V AC, 50/60 Hz, Max. rated power when in combination with other units: 155 VA) External power supply (10 to 30 V DC, Max. rated power: 60 VA) | |
| Output connector | HIOKI ME15W (male)* | |
| External dimensions | 116 mm (4.57 in) W x 67 mm (2.64 in) H x 132 mm (5.20 in) D | |
| Mass | 420 g (14.8 oz) | |
| Accessories | AC ADAPTER Z1002, Power cord, Instruction Manual | |

* CT9904 (sold separately) is required to connect to PW3390

* CT9920 (sold separately) is required to connect PW3390 to the sensor with HIOKI PL14 on the output connector.

Model : POWER ANALYZER PW3390

| Model No. (Order Code) | D/A output | Motor analysis |
|------------------------|------------|----------------|
| PW3390-01 | - | - |
| PW3390-02 | 0 | - |
| PW3390-03 | 0 | 0 |

Accessories: Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable ×1, Input cord label ×2, D-sub 25-pin connector ×1 (PW3390-02, PW3390-03)

. The optional voltage cord and current sensor are required for taking measurements.

• Motor analysis and D/A output cannot be changed or added after delivery

Current Measurement Options

| Name (Note) | Model No. (Order Code) |
|---|------------------------|
| AC/DC CURRENT SENSOR (50 A) | CT6862-05 |
| AC/DC CURRENT SENSOR (200 A) | CT6863-05 |
| AC/DC CURRENT SENSOR (500 A) | 9709-05 |
| AC/DC CURRENT SENSOR (1000 A) | CT6865-05 |
| AC/DC CURRENT PROBE (20 A) | CT6841-05 |
| AC/DC CURRENT PROBE (200 A) | CT6843-05 |
| AC/DC CURRENT PROBE (500 A, φ 20 mm (0.79 in)) | CT6844-05 |
| AC/DC CURRENT PROBE (500 A, φ 50 mm (1.97 in)) | CT6845-05 |
| AC/DC CURRENT PROBE (1000 A) | CT6846-05 |
| CLAMP ON SENSOR (AC 20 A/200 A) | 9272-05 |
| AC/DC CURRENT BOX (50 A, 3 ch) | PW9100-03 |
| AC/DC CURRENT BOX (50 A, 4 ch) | PW9100-04 |
| AC/DC AUTO ZERO CURRENT SENSOR (2000 A) | CT7742 * |
| AC/DC CURRENT SENSOR (2000 A) | CT7642 * |
| AC FLEXIBLE CURRENT SENSOR (6000 A, \$\$\phi\$ 100 mm (3.94 in)) | CT7044 * |
| AC FLEXIBLE CURRENT SENSOR (6000 A, ¢ 180 mm (7.09 in)) | CT7045 * |
| AC FLEXIBLE CURRENT SENSOR (6000 A, ¢ 254 mm (10.00 in)) | CT7046 * |
| SENSOR UNIT (Sensor power supply with 4 channel summing function) | CT9557 ** |

* CONVERSION CABLE CT9920 is required to connect to PW3390. ** CONNECTION CABLE CT9904 is required to connect to PW3390.

Voltage Measurement Options

VOLTAGE CORD L9438-50

VOLTAGE CORD L1000

1 WIRING ADAPTER PW9000

Connection Options

CONNECTION CORD L9217

CONNECTION CABLE 9683

(9.84 ft)

Red, black: 1 each 1000 V specification. Cord length: 3 m (9.84 ft) CAT IV 600 V. CAT III 1000 V

Red, yellow, blue, gray: 1 each; Black: 4 1000 V specification, Cord length: 3 m

CAT IV 600 V, CAT III 1000 V

When making a 3-phase 3-wire

voltage cords from 6 to 3.

BNC-BNC. For motor analysis input Cable length: 1.6 m (5.25 ft)

(3P3W3M) connection, this product allows you to reduce the number of

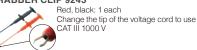
For synchronous measurement,

Cable length: 1.5 m (4.92 ft)



Red, black: 1 each, With connector, Cable length: 1.5 m (4.92 ft) For extension of L9438-50 or L1000 CAT IV 600 V. CAT III 1000 V

GRABBER CLIP 9243





connection, this product allows you to reduce the number of voltage cords from 6 to 4.

LAN CABLE 9642 Supplied with straight to cross conversion connector, Cable length: 5 m (16.41 ft)

RS-232C CABLE 9637 9pin-9pin cross Cable length: 1.8 m (5.91 ft)

CONVERSION CABLE CT9900

Required to connect PW3390 to the current sensor with HIOKI PL23 on the output connector.

[Applicable products] CT6841, CT6843, CT6844, CT6845, CT6846, CT6862, CT6863, 9709, CT6865, 9272-10

CONVERSION CABLE CT9920



Required to connect PW3390 to the current sensor with HIOKI PL14 on the output connector.

[Applicable products] CT7742, CT7642, CT7044, CT7045, CT7046

CONNECTION CABLE CT9904



Cable length: 1 m (3.28 ft) Required to connect the summing waveform output terminal of CT9557 to PW3390. [Applicable products] CT9557

Built-To-Order (Current Measurement)

PW9100 5A-rated model 9709-05 high-accuracy model CT6862-05 high-accuracy model CT6863-05 high-accuracy model

Please contact your Hioki distributor or subsidiary for more information.

AC/DC 2000 A high accuracy sensor, pass-through type

Other Options

PC CARD 512 MB 9728 PC CARD 1 GB 9729 PC CARD 2 GB 9830



Use only PC Cards sold by HIOKI. Compatibility and performance are not guaranteed for PC cards made by other manufacturers. You may be unable to read from or save data to such cards.

CARRYING CASE 9794



Carrying Case for PW3390 and 3390 448 mm (17.64 in) W x 618 mm (24.33 in) H x 295 mm (11.61 in) D

Rackmount fittings

D-sub 25-pin - BNC (male) 16 ch conversion, Cord length: 2.5 m (8.20 ft)

Built-To-Order (Other)

D/A output cable

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